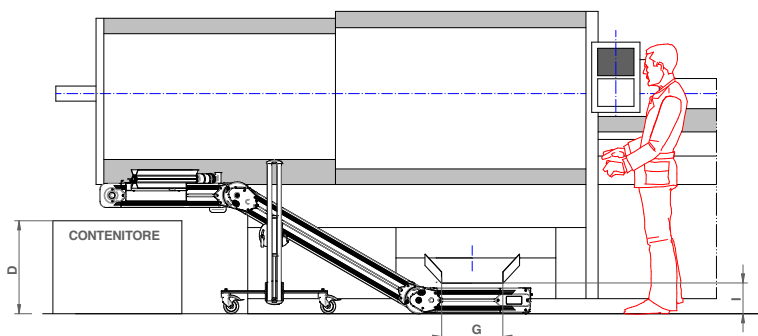
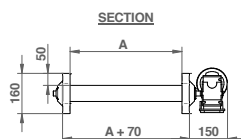


technical features

- Structure made of aluminium anodized profile height 160 mm
- With side panel not removable h 50 mm
- PVC high grip belt without slats, vulcanised belt joint.
Temperature resistance -10°C to +60°C
- Upper flat part equipped with paddle separator model WP complete of a lateral unloading chute
- Conveyor's transmission group composed of: three-phase asynchronous motor, worm reduction unit with lubrication for life
- Paddle separator's transmission group composed of: three-phase asynchronous motor, worm reduction unit and torque limiter
- Fixed standard speed ~3 m/min
- Equipped with Start/Stop motor cut-out
- Standard motor supply voltage 400V/50 Hz



required dimensions

A (mm) 140 240 340 440

D (mm) _____

G (mm) _____

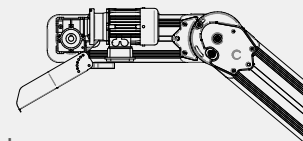
I (mm) _____

capacity Kg _____

material to convey _____

specify presence of
lubrificant colorant or
or other fluid
if present _____

optional

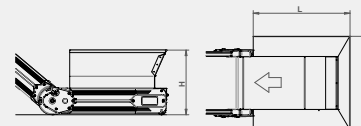


UNLOADING CHUTE

standard unloading chute

LOADING HOPPER

loading hopper



CONVEYOR BELT

high grip:
high grip grey colour without slats

high grip :
high grip grey colour with slats 12x12 mm and pitch _____ mm

TRANSMISSION GROUP

Mounted on the LEFT side

CONTROL PANEL - REQUIRED FUNCTIONS

START / STOP (standard)

INVERTER
independently from the functions programmed in the control panel, it is always possible to adjust the conveyor speed

ROBOT - PULSE
a clean signal coming from the Robot decides the Start of the conveyor. When the running time is over the control panel stops the conveyor and waits for the next signal to repeat the cycle. The panel is complete with a plug for its connection to the external signal

FEEDER
a clean signal coming from the Robot decides the Start of the conveyor. The conveyor runs for the duration of the signal coming from the Robot. The panel is complete with a plug for its connection to the external signal

PAUSE - WORK
programming the control board in this function, it is possible to set the conveyor's STOP and WORK time, causing his intermittent advancing, independently from any external signal

NOTE
